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Real-time Simulations on High-Performance Z-Source PV-Grid-Tied Inverters with DC Charger for EV Applications

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Abstract

Solar power is the most prevalent green energy source for household and semi-commercial applications. Using energy storage devices, fluctuations in solar energy collecting can be reduced (ESS). Solar electricity can also be utilized to charge electric vehicle batteries, reducing reliance on the grid. To qualify as such converters, they must have a limited number of steps and a separation. It is possible to eliminate multiple stages of conversion by using the Z-source inverter (ZSI) topology. The use of passive materials allows for the incorporation of ESS. To charge the batteries of electric vehicles using direct current, this article describes the design, building, and operation of a modified ZSI equipped with a split primary separated battery charger. Simulated results have been used to demonstrate the feasibility of the proposed converter's operation.

Keywords: SRM, Inverter, EV, and speed/load.

1. Introduction

Currently, the AC grid is frequently utilized for charging electric vehicles. Regardless of how effective the topology is, various charging techniques that only use an AC grid, such as wireless charging or plug-in charging, can still generate pollution. While charging an electric vehicle, it's important to know how much fossil fuels are used to generate the electricity needed. Renewable energy sources can be integrated into charging infrastructure to lessen the need for electricity from the main grid [1]. Isolation transformers in converter topologies enable galvanic isolation at the user end of the high-voltage system in order to give safety measures when creating an EV battery charger. It is possible to achieve galvanic separation on either the charger or the ac grid side [2]. On the grid side, isolation transformers tend to be significantly larger than those on the charging side. Highfrequency switching has made it possible to employ smaller transformers for galvanic separation because of improvements in semiconductor technology [3].

It has been utilized in the past for commercial charging infrastructure with photovoltaic (PV) grid connection systems They reduce the need for an AC power grid to supply charging infrastructure. Residential charging systems for electric vehicles (EVs) can benefit from using solar and grid-connected systems [4]. Single-phase inverters with a power output of up to 10 kW can be used in residential settings. There are a variety of isolated and non-isolated topologies with many stages available for connecting residential solar PV to the grid. For EV charging, residential PV systems need features such as isolation and voltage boosting capabilities to match the solar PV array voltage to the grid voltage needs [5]. [5

Single-stage bucking or boosting and inversion of the input dc voltage are all possible. A lot of

attention has been paid to PV-grid-connected systems. An inverter based on Z-Source(ZSI) topology uses two capacitors and two inductors to boost the input dc voltage tomatch the inverter-side ac output voltage requirements. The operation of a ZSI is heavilydependent on the passive components [6]. It presents an opportunity to integrate energystorage units into such a system. In this project, a proof of concept of a singlephaseModifiedZ-

sourceInverter(MZSI)basedsolargridconnectedchargerhasbeenpresentedasan applicationtowarda stringinverterconfiguration.



Figure1.SchematicofaPV/acGridInterconnectedZSI



Figure2.Detailed SchematicoftheProposedMZSI

1.2 **Literature Survey**

This work by D. Aggeler et al. [7] focuses on PF newlv developed infrastructure technologies that enable quick battery charging operations. Now more than ever, Power Electronics (PE) is finding its way into several technical fields. One of these is electric mobility. Energy distribution for charging and energy transformation on board of the traction-related vehicles are just two examples of how Power Electronics presents itself as an emerging technology for improving sustainable mobility. In less than 10 minutes, depending on the battery and vehicle, a charge adequate for a trip distance of over 100 kilometers can be obtained [8]. It's only a matter of time before battery charging is as quick and easy as filling up at a gas station right now. On the basis of low- and highfrequency isolation requirements, two PE converter topologies for charging infrastructure applications are described and explored. The pros and cons of each of the two technologies will be discussed, as well as the advantages and disadvantages of each. Studying the grid's effect is done bymeansof simulation with theassumption of a dc fast chargingstationplaced in а ruralareain Sweden.

G. Carliand S. S. Williamson [9], analyzesonespecifictypeofrenewable,

localenergy generation, applied to electric vehicle charging requirements. It is now clear thatthe transportation sector will increasingly relv on electricity and the related infrastructureneeded for storage and distribution. At the same time, the source of electricity itself mustnot be carbon based.

Rather, whenever possible, it should depend on

environmentallyresponsibleprocesses.Inadditi ontotheirecologicalbenefits, aeolicand photovo Itaic(PV) sources are highly scalable, and can be utilized for local generation and delivery, eliminating those energy losses normally associated with long-range grid distribution. APV source is explicitly posited, because solar panels can be placed above the vehicleparking space, and double as a shade provider. In the first part of this paper, the optimalrequirementsforoverallsystemarederiv ed.Thesewillbeusedinthesecondpart, in the purpose of comparing various power conditioning circuits

[10] discusses the construction of a discrete event simulation framework that emulating the interactions between the power grid and plug-in hybrid electric vehicles and investigates if existing capacity can fulfill the PHEV load requirement of the current power system. Statistical transportation data is used probability distribution to extract the functions for each vehicle's arrival time and energy use. The inadequate generating and transmission capabilities of the electric system are seen as the key limitations. Because of this, vehicles may have to wait for a charge to arrive. Two real-world examples in the United States are used to demonstrate the validity of the suggested simulation framework, which is detailed in depth. We're thinking about both Level-1 and Level-2 charging options.ProblemFormulation

If the dc-rail voltage exceeds the ac-input voltage, the ac output voltage is capped below the dc-rail voltage. That is why an inverter for the voltage source converts voltage from one form to another: from one form to the other, the inverter acts as a boost (step-up) rectifier and the voltage source converter acts as an ac-to-dc inverter. When a higher ac output voltage is required but the existing dc voltage is insufficient, a second dcdc boost converter is required. Cost and efficiency are lowered by an additional power converter stage.

For each phase leg, there is no way to turn on both the upper and lower devices at the same time. Otherwise, the devices would be destroyed by a shoot-through. One of the biggest threats to a converter's dependability is the misgating-on shootthrough problem caused by EMI noise. The voltage source converter must provide dead time to block both upper and lower devices, resulting in waveform distortion and other problems. A current-source inverter cannot produce a sinusoidal voltage without the use of an output LC filter, which results in increased power loss and management complexity.

The dc voltage produced by the dc inductor is always smaller than the ac input voltage 2. Formatting your Paper

3. To put it another way, a photovoltaic (PV) cell is nothing more than a p-n junction diode.

because the ac output voltage must be greater than the original dc voltage that feeds the dc inductor. There is a buck converter (or current source rectifier) and a boost converter (or current source inverter) for dc-to-dc power conversion in the current source inverter. Additional dc–dc buck (or boost) converters are required for applications that require a large voltage range. Cost and efficiency are both impacted by an additional power conversion stage. In order to use highspeed and high-performance transistors like insulated gate bipolar transistors, the main switches of the current source converter must prevent reverse voltage (IGBTs). To avoid direct usage of low cost and highperformance IGBT modules and intelligent power modules (IPMs).

This paper presents an impedance-source (or impedance-fed) power converter (abbreviated as Z-source converter) and its control method for implementing dc-to-ac, ac-to-dc, ac-to-ac, and dc-to-dc power conversion in order to overcome the above problems of traditional voltage source and current source converters.



There is a simple equivalent circuit schematic of a PV cell in Figure 3. PV cell generated current is represented by a current source, which is in parallel with a diode and shunt and series resistances.

Figure3Equivalentcircuitdiagram of the PVcell

4. DC-DC Converters

DC-DC converter having a high step-up voltage that can be utilized in a variety of applications, including automotive headlights, fuel cell energy conversion systems, solar cell energy conversion systems, and uninterruptible power supply battery backup systems. Theoretically, a high effective duty ratio dc-dc boost converter can achieve a high step-up voltage. The step-up voltage gain is limited in practice by the influence of power switches and the ESR of inductors and capacitors, though.

To get a high step-up voltage gain with a high duty ratio, a traditional boost converter is typically employed. However, the losses of power switches and diodes, the equivalent series resistance of inductors and capacitors, and the reverse recovery difficulty of diodes limit the efficiency and voltage gain. In these converters, considerable voltage stress and power dissipation are caused by the active switch because of the transformer's leakage inductance. It is possible to decrease the voltage surge by using a resistor-capacitordiode snubbed combination. However, this results in a decrease in effectiveness. Converters with low input ripple current are generated using a connected inductor. An extra LC circuit with a connected inductor is

used to achieve reduced input current ripple in these converters.

5. Inverter

Direct current (DC) can be converted to alternating current (AC) using proper transformers, switching, and control circuits, and the AC can be at any desired voltage and frequency. Small computer power supply to huge electric utility high voltage direct current applications can all benefit from using static inverters, which have no moving components and are employed in a wide range of applications. To convert DC electricity into AC inverters are often power, employed.suchassolarpanelsorbatteries.Theel ectricalinverterisahighpowerelectronicoscillat or. It is so named because early mechanical AC to DC converters made to work inreverse, and thus "inverted", to convert DC to AC.

4.1 CascadedH-BridgesInverter

Figure 4 depicts the single-phase structure of a cascaded inverter. A single phase full bridge inverter, often known as an H-bridge, is used to connect each individual DC source (SDCS). There are three alternative voltage outputs for each inverter level that can be generated by connecting the DC source to the DCdc ac output in different ways. fourS1, S2, S3, and S4 are the on/off switches. Switches dc S1 and S4 are used to produce +Vdc, whereas S1 and S3 are used to produce –Vdc. The output voltage is 0 when S1 and S2 or S3 and S4 are turned on. These inverters are connected in series to produce a voltage waveform that is the sum of their AC outputs, which can be used to control other devices. In a cascade inverter, the number of output phase voltage

levels m is specified as m = 2s+1, where s is the number of distinct DC sources. For an 11level H-bridge inverter with five SDCSs and five complete bridges, a phase voltage waveform is illustrated in Figure 5. The voltage across each phase + ...(1) Forasteppedwaveformsuchastheonedepictedi nFigure5withssteps,theFourierTransformforth iswaveformfollows



Figure4.Single-phasestructureof amultilevel cascadedH-bridgesinverter



Figure 5 Output phase voltage waveform of an 11 level cascade inverterwith5separate dcsources

6. ProjectDescriptionandControlDesign

5.1 TraditionalZSI

5.2 Figure 7 depicts the ZSI structure in two operational modes: shoot-through and non-shoot-through. VC = VC1 = VC2 is the formula for symmetrical operations. In the shoot-through mode, all four switches are engaged.

At the same time, SA, SB, SC, and SD are conducting. The duty cycle D0 and switching frequency F0 are used to characterize the length of this shoot-through state (FSW). A modified pulse width modulation (PWM) approach can be used to implement the shoot-through condition. As a result, the voltages between the two capacitors are written as Using the VPN's peak dc-link voltage,

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VPN is defined as 1/(12D0)vpv (4)

. IgrmsVgrms is the power balance equation between the ac and dc sides of the ZSI (5)

. The maximum dc-link current and voltage are denoted by IPN and VPN, respectively. The ZSI's maximum ac output voltage is

. In other words, Vg is equal to MVPN (6)

. Vg is the grid voltage modulation index.

. For grid-connected applications, the grid current ig = Ig sin (t+) for = 0 The ZSI's output ac voltage's RMS value can be calculated from (11) and (13).

VC = (1 - D0)/(1 - 2D0) vpv (3)

It can be shown that Mvpv/(1 2D0) is equivalent to Vgrms (7)



Figure 6. Schematic of one the primary across CHB1 operating at 50% duty cycle

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ComponentSizing,Modeling,andContr oloftheProposedMZSI

MZSIs with integrated battery chargers are depicted in Figure 7. A split primary isolated half-bridge bidirectional operation of the MZSI is achieved by splitting the two capacitors (C1 and C2) from Figure 6, with each serving as one leg. To prevent the reverse flow of current back into PV, the diode DPV is used. Cin's input capacitor Rin has an internal resistance of Rin. Proposals have been made for the integration of the charger within the ZSI using a split primary dc-to-dc converter. One complete bridge secondary is isolated from a pair of HBC primaries using a highfrequency transformer. In an open loop, the HBC primary and secondary processors run at 50% duty cycle. The secondary's output current is routed to a power source, such as a lithium-ion battery. Since the HBC primary input voltages VC and vB are clamped together at the energy storage unit's input,

Each of the split primaries alternates between charging and providing half of the battery current. It is connected across the capacitors of each leg of the dc–dc converter's primary. The voltage applied across the capacitors is given by the expression: (15). In the simplified equivalent model shown in Figure 7, each of the two primary can be represented by an RLE circuit linked in series with the capacitors C1 and C2. As shown in Figure 7, the Kirchhoff's voltage law (KVL) equation can be applied to the modeled MZSI in the non-shoot-through state.LdiL/dt=vpv-iLr+RHB+(2ig+iB/2)RHB–VC

.....(12)TheKirchhoff'scurrentlaw(KCL)

equationis

CdVC/dt=iL-ig-iB/4

.....(13) During the shootthrough state, the KVL equation is

LdiL/dt=VC-iL(RHB+r)-(iB/2)RHB(14)

TheKCLequationiswrittenas

CdVC/dt=-iL-iB/4(15)



Figure7.Equivalentmodel of the proposed MZSI with a battery



Figure 8. Block diagram of the control scheme of the proposed MZSIcharger

5.24 Figure 7 depicts the battery current iB and the grid ac current ig flowing in the right direction. Figure 8 depicts the controller block diagram for the proposed MZSI topology

through duty ratio D0 is generated by controlling the voltage of the ZSI capacitor. By adjusting the maximum input PV current, a reference current is generated. In this case, the shoot-through duty ratio D0 is dependent on the stiff voltage VC applied across one or both capacitors. Battery loop control is slower controller. The PV current ipv loop, the grid current ig loop, and the battery current iB loop make up this system's three loops. Hbridge inverter output current or shoot-

than input current control because the battery current loop does not require rapid dynamic changes. For the control of the battery loop.

5.25

EnergyManagementSchemeforthePr oposedConverter Block schematic of the proposed system shown in Figure 8. ZSIs that include an energy storage system (ESS) alter the formula (5) as follows: Vbib + Igrmsvgrms...(18) where Ib and vb are the battery current and voltage, respectively. A constant charging power PB is obtained at the ESS due to the single-phase ac grid power Pg balancing the power fluctuations of the PV source Ppv. When pulling power from the grid to charge an EV battery, the direction of the ac grid current flow switches from positive to negative. The charger is powered by PV and the grid, which means that the inverter may run in both directions and keep the system in a powerbalanced state.

the sum of the parts VPV + igrmsvgrms = vbib.. (19)

A grid-connected rectifier/charger can be used in the absence of PV if the voltage across the input capacitor Cin is maintained at the minimum value of the PV voltage.

7. Simulation Results

The simulation studies to demonstrate the behavior of the proposed topology have beencarried out using PLECS 4 for a 3.3 kW charger for а string inverter configuration.Simulationhasbeencarriedoutfor thesystemshowninFigure9showsthatatasimula tion time t = 1.75 s, the input PV power reduces from 2.8 to 2 kW and the gridpowerincreasesfrom710to1500 Wtomaintaintheoutputcharger powerto 3.3kW.



Figure9.Overall Simulink diagram

Table1.MZSI-BasedChargerSystemSimulationSpecifications

S.No	ParametersValu e	Value
1	Inputvoltage, Vin	286V
2	Inputcurrent, Iin	9.8A
3	Inductorvalue,L1=L2	500µH
4	ZSIswitchingfrequency,FSW	25kHz
5	Gridvoltage(RMS),Vg	240V
6	Inverteroutputfilterinductor,Lf	7.5mH

7	PVinputpower, PPV	2.8kW
8	Inputcapacitor,Cin	2mF
9	HBCoutputfilter,LB	1mH
10	HBCoutputfilter,LB	1mH
11	Batterychargepower,PB	3.3 kW



Figure10.OutputwaveformofGridcurrent

The above figureshowsoutputwaveformofgridcurrent.Int

hisX-axisrepresentstimeinsecondsandYaxisrepresentsgridcurrentinamperes.



Figure 11. Output wave form of DClinkvoltage

The above figureshowsoutputwaveformofDClinkvoltage.InthisX-axisrepresentstimeinsecondsandY-axisrepresentsDClinkvoltageinvolts.



CapacitorVoltage

Figure12.Outputwaveformofcapacitorcurrent

The above figures how soutput wave form of capa citor current. In this X-

axisrepresentstimeinsecondsandYaxisrepresentscapacitorcurrentinamperes.



Figure 13. Output wave form of battery current

The above figures how soutput wave form of battery current. In this X-axis represents time in seconds and Y-axis represents battery current in amperes.

Figure14.OutputwaveformPVpower

 $\label{eq:constraint} The above figure shows output waveform of {\sf PV} power. In this X-axis represents time in second s and Y-axis represents power in watts.$

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300				
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5.0				
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64.				
- 1	0	5	 5	5

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Figure15.OutputwaveformofGridPower

 $\label{eq:constraint} The above figure shows output wave form of grid power. In this X-axis represents time in second s and Y-axis represents grid power in watts.$



Figure 16. Simulation waveform for the power balance between the PV inputpower, the acgridside, and the battery power

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Conclusion

For PV-grid-connected charging systems, this article recommends a MZSI structure. For charging or energy storage, it has a singlestage PV-grid connection and an integrated charger. In semi-commercial settings like a shopping center parking lot, this topology can be employed in clustered charging configurations. When using string inverters for residential use, the charger side can be connected in series or parallel for current sharing. A Z-source converter's impedance network can be used to create a symmetrical energy storage topology, according to this paper.

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